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Notes on how to proceed further You should always refer to the function diagrams first graphic illustration of functions before carrying out further parameterization process data control values, setpoints and actual values, functions etc. or diagnosis. They can be found in the appendix of the Compendium. The function diagrams are subdivided into those for basic functions, free function blocks and supplementary boards EBx, SCBx. Use the list of contents at the beginning of the function diagrams to look for functions. First read the following pages. Reference is given there to the relevant page number of the associated function diagram. 2 6SE70876QX60 Version AG Siemens AG Compendium Vector Control SIMOVERT MASTERDRIVES 10.2004 Guidelines for StartUp. He or she must have the following qualifications. Trained or authorized to energize, deenergize, ground and tag circuits and equipment in accordance with established safety procedures. Trained or authorized in the proper care and use of protective equipment in accordance with established safety procedures. Trained in rendering first aid. DANGER indicates an imminently hazardous situation which, if not avoided, will result in death, serious injury and considerable damage to property. WARNING indicates a potentially hazardous situation which, if not avoided, could result in death, serious injury and considerable damage to property. CAUTION used with the safety alert symbol indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury. CAUTION used without safety alert symbol indicates a potentially hazardous situation which, if not avoided, may result in property damage. NOTICE NOTICE used without the safety alert symbol indicates a potential situation which, if not avoided, may result in an undesirable result or state. Siemens AG 6SE70876QX60 Version AN SIMOVERT MASTERDRIVES Compendium Vector Control 1 Definitions and Warnings WARNING 08.

2012 Hazardous voltages are present in this electrical equipment during operation. Nonobservance of the warnings can thus result in severe personal injury or property damage. Only qualified personnel should work on or around the equipment This personnel must be thoroughly familiar with all warning and maintenance procedures contained in this documentation. The successful and safe operation of this equipment is dependent on correct transport, proper storage and installation as well as careful operation and maintenance. NOTE This documentation does not purport to cover all details on all types of the product, nor to provide for every possible contingency to be met in

connection with installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the local SIEMENS sales office. The contents of this documentation shall not become part of or modify any prior or existing agreement, commitment or relationship. The sales contract contains the entire obligation of SIEMENS AG. The warranty contained in the contract between the parties is the sole warranty of SIEMENS AG. Any statements contained herein do not create new warranties or modify the existing warranty. Proper use of Siemens products WARNING 2 Siemens products may only be used for the applications described in the catalog and in the relevant technical documentation. If products and components from other manufacturers are used, these must be recommended or approved by Siemens. Proper transport, storage, installation, assembly, commissioning, operation and maintenance are required to ensure that the products operate safely and without any problems. The permissible ambient conditions must be adhered to. The information in the relevant documentation must be observed. 6SE70876QX60 Version AN Siemens AG Compendium Vector Control SIMOVERT MASTERDRIVES 08.

2012 Definitions and Warnings Residual risks of Power Drive Systems PDS DANGER The components for the controller and drive of a Power Drive System PDS are authorized for industrial and commercial use in industrial networks. It is only permissible to operate these components in enclosed housings or in superordinate control cabinets and when all protective devices and protective covers are used. These components may only be handled by qualified and trained specialist persons who are familiar with and observe all the safety instructions on the components and in the relevant technical user documentation. For additional information on the residual risks emanating from the components of the PDS, please refer to the relevant chapters of the technical user documentation. Siemens AG 6SE70876QX60 Version AN SIMOVERT MASTERDRIVES Compendium Vector Control 3 Definitions and Warnings DANGER 08.2012 Electrical, magnetic and electromagnetic fields EMF that occur during operation can pose a danger to persons who are present in the direct vicinity of the product especially persons with pacemakers, implants, or similar devices. These state that a hazard analysis must be drawn up for every workplace, from which measures for reducing dangers and their impact on persons are derived and applied, and exposure and danger zones are defined and observed. The safety information in the Storage, Transport, Installation, Commissioning, Operation, Maintenance, Disassembly and Disposal sections must also be taken into account. DANGER Commissioning, operation and maintenance are only to be carried out by qualified personnel who are familiar with and adhere to the safety instructions in the respective documentation. The documentation can be ordered through your local SIEMENS office. NOTE for UL applications To provide thermal memory retention and speed sensitivity in accordance with UL508C, rev. Nov. 9th, 2010, a motor temperature sensor must be connected.

This product group represents an overall modular, fully digital component system for solving all drive tasks posed by three-phase drive engineering. The availability of a high number of components and the provision of various control functionalities enable it to be adapted to the most diversified applications. Control functionality The control functionality is determined by the software stored in the inverter and converter modules. The following different control versions are provided within the SIMOVERT MASTERDRIVES product group. Motion control MC Vector control for servo applications, optionally with higher-level technology functions Components The SIMOVERT MASTERDRIVES product group comprises the following components. Active front end AFE incoming units. Braking units and braking resistors. DC link bus for cabinet units. Interference suppression filter. Line commutating reactor. Technology modules. Optional boards o Sensor boards SBx for speed and position sensing o Communication boards CBx for field bus interfacing o SIMOLINK SLx for fast transmission of setpoints and actual values. Accessories Siemens AG 6SE70876QX60 Version AN SIMOVERT MASTERDRIVES Compendium Vector Control 11 System Description 1.2 10.2001 System description The Vector Control functionality is matched to the drive system requirements.

The vector current control enables fast current injection into the motor windings in conjunction with short sampling times. The related highly dynamic buildup of the torque provides a good basis for higherlevel closedloop control circuits. The current control types are available both without and with various different encoder types for speed acquisition for asynchronous motors. As a special application, externally excited synchronous machines can be operated in control type speed control with encoders current control type.

All units are provided with a comprehensive basic functionality which can be expanded, if required, by extensive technology and communication functions by the use of software and hardware options. This enables the units to be adapted to the most diversified conditions of service. All closedloop control functions are implemented with freely assignable function blocks which can be combined as desired. This enables the software to be flexibly adapted to various applications. Menu structures stored in the unit software simplify startup and visualization of the drives in conjunction with various operator control panels. PCassisted tools enable effective parameter setting and data security. 12 6SE70876QX60 Version AG Siemens AG Compendium Vector Control SIMOVERT MASTERDRIVES 10.2001 Performance features 1.3 System Description The units with Vector Control functionality have the following performance features. Available as a converter and as an inverter module. Output range from 0.55 kW to 2300 kW Various configurations possible for multiaxis drives. Integrated DC link bus module and fusing. Integrated USS interface for the configuration of simple bus systems. Interfacing of various field buses o PROFIBUS o CAN bus. Drive networking with up to 200 nodes via SIMOLINK. Integrated technology functions for positioning, synchronism and cam disk. Startup and diagnostics functions. Comprehensive converter functions o Restart on the fly o Kinetic backup o Automatic restart o Flexible yielding o DC braking. Menu prompting Graded operator control and visualization by means of an integrated simple standard operator control panel, a userfriendly operator control panel or via PC. Uniform PCcapable programming software DriveMonitor. In accordance with the currently applicable European standards, CE designation. Compact PLUS type 0.55 kW to 18.5 kW Siemens AG 6SE70876QX60 Version AG SIMOVERT MASTERDRIVES Compendium Vector Control 13 System Description 1.4 10.

2001 Communication A differentiated communication concept makes it possible to use the correct communication medium depending on the requirements. The following communication interfaces are available. Integrated serial interfaces with USS protocol for parameter setting, operator control and visualization of the units with OP1S or PC. Optional boards for various field bus interfaces e.g. Profibus DP for integration in the automation. Optional board for interfacing SIMOLINK for fast data exchange between technologically linked drives or peertopeer for transfer of technological digital setpoint and actual values between the drives. For this purpose, a converter is used that is directly connected to the 3phase supply via an external main contactor, a line filter and a line reactor as necessary. Any regenerative energy is stored in the capacitor module or reduced in the braking resistor. 2.1.2 Multiaxis drive up to 3 axes In the case of multiaxis drives see Fig. 22 a converter ACAC can be combined with inverters DCAC. The converter rectifies the line voltage and supplies the inverters with direct voltage via the DC link bus module. The power supply integrated in the converter further provides the 24 V supply voltage for the electronics of a maximum of 2 inverters. CAUTION If more than 2 inverters are connected, the 24 V supply for the electronics must be provided by an external power supply. The total rated output currents of the inverters supplied by a converter must not exceed the rated output current of the feeding converter in the case of 6SE70210EP60 only half the rated output current. The regenerative energy generated in one axis can either be used up by the other motors, stored in the capacitor module or reduced in the braking resistor. Siemens AG 6SE70876QX60 Version AM SIMOVERT MASTERDRIVES Compendium Vector Control 21 Configuration and Connection Examples 2.1.3 12.2010 Multiaxis drive In the case of multiaxis drives see Fig.

23 with more than 3 axes, several inverters are connected to the line voltage via a common rectifier unit. An external power supply is required for the 24 V supply voltage for the inverter electronics. The need for the individual components must be clarified according to the given application. A radio interference suppression filter is required whenever the radio 3 Radio interference voltages originating from converters or rectifier units must interference suppression filter be reduced according to EN 618003. 4 Line commutating reactor The line commutating reactor limits current peaks and reduces harmonics. The chassis units are connected for inverter via X181.5 and the compact units are connected directly to fan fuses devices F101 and F102. Siemens AG 6SE70876QX60 Version AM SIMOVERT MASTERDRIVES Compendium Vector Control 213 Configuration and Connection Examples 10 24 V auxiliary power supply 12.2010 The external 24 V power supply serves to back up the communications and diagnostics functions of the connected devices when the line voltage is switched off. Rectifier units always require an external 24 V power supply. The following criteria apply to dimensioning. Currents see Catalog DA65.10 When the 24 V supply is switched in, an inrush current has to be dealt with by the power supply. There is no need to install a stabilized power supply; the voltage range must be kept between 20 V and 30 V. 11 X300 serial interface The serial interface is used for connecting the OP1S operator pane or a PC. It can be operated according to the RS232 or the RS485 protocol, as desired. Siemens 5TT3407 suitable for TN systems. Depending on the requirements of the system, this input is assigned function AUS2 trip command with direct pulse disable P557.i and disables the thyristors to avoid a commutation failure very effectively. This function prevents unexpected starting of the motor from standstill that is connected to the drive control unit.

This is the reason that this safety function may be activated only after the drive actually comes to a standstill. Otherwise, it will not be able to brake. MC Motion Control VC Vector Control The control variant does not influence the internal and external safety circuitry. Pulse disconnection by the safety relay which is needed to implement the STO function is always performed on the power module. This is the case irrespective of the control variant. There are various methods of achieving safe pulse suppression depending on the type of construction. Type of construction Unit rating Safety circuit design Compact PLUS Small 0.55 kW to 4 kW As a separate module on the power section option K80 Compact PLUS Large 5.5 kW to 18.5 kW On the power section option K80 Compact PLUS Large LE 22 kW to 37 kW As a separate module on the power section option K80 Compact converter 18.5 kW to 37 kW On power section module PEU Compact inverter 2.2 kW to 37 kW On power section module PEU Chassis 1 45 kW to 200 kW Implemented by SSB module option K80, piggyback on PSU1 power supply Chassis 2 250 kW to 1.2 kW SSB module option K80 as for Chassis 1, but directly integrated in the unit Siemens AG 6SE70876QX60 Version AM SIMOVERT MASTERDRIVES Compendium Vector Control 221 Configuration and Connection Examples Fig. 210 12.2010 Schematic diagram of MASTERDRIVES Compact PLUS converter with K80 board The power section controls the power feed to the individual motor windings. The control logic on the control board drives the 6 power transistors in a particular pattern in order to generate a rotating field. In order to provide electrical isolation, an optocoupler or fiber optic cable is connected between the control logic and each control amplifier of a power transistor. The power supply PV of the optocouplers or fiber optic cable transmitters is supplied via the NO contact of safety relay K1.

Because the NO and NC contacts are positively driven, it is possible to evaluate the status of the safety relay NO contact from the checkback contact NC contact. It does not therefore provide any protection against electric shock. 222 6SE70876QX60 Version AM Siemens AG Compendium Vector Control SIMOVERT MASTERDRIVES 12.2010 Configuration and Connection Examples The safety relay circuit including its internal layout is always identical. This means that the same circuit principle can be applied on all unit types. However, the terminal designations differ according to the unit type. STOP B Stop Category 1 Quick stop It should be noted that the safety functions represent only a very small minority of the device functions. Through selection of appropriate circuitry, it is

possible to build a twochannel structure with appropriate fault detection mechanisms for safety functions. The line contactor and the line fuses in the feeder cable must be designed and dimensioned in accordance with the specifications given in catalogs DA 65.10 and DA 65.11 or the Engineering Information. Every safety function must be constructed of appropriate sensors, logic units and actuators. The subsystems ACQUIRE and EVALUATE are not examined in detail here. The components must be selected and designed according to the requirements of the safety function to be implemented. The subsystem REACT is in principle a twochannel structure. The first channel contains the safety relay K1 of the drive option K80. This operates according to the principle of pulse disconnection with monitoring. The second channel is formed by the line contactor K2 which must be connected into the mains feeder cable. The line contactor is monitored by the positively driven NC contact. As an alternative to integrating the line contactor, it is also possible to use one motor contactor for each motor as a second safety channel. The calculation results for the example applications below can be applied analogously.

Siemens AG 6SE70876QX60 Version AM SIMOVERT MASTERDRIVES Compendium Vector Control 225 Configuration and Connection Examples 2.4.4.2 12.2010 SS1 principle in a safety function Fig. 213 SS1 principle, twochannel structure By adding appropriate circuit components, the SS1 safety function can be implemented on the basis of the STO function. In this case as well, the function architecture is essentially twochannel. A safetyoriented dropout delay must be added to the subsystem EVALUATE. Activation of the safety function by the subsystem ACQUIRE initiates an instantaneous, singlechannel quick stop on the drive. A safe timer is started simultaneously in EVALUATE. The dropout delay of the timer must be set such that the drive can decelerate down to zero speed along the quick stop ramp before the timer runs down. However, the terminal designations and connection locations may differ according to the unit type. The circuit examples given below can be adapted for application on all types of MASTERDRIVES converter. The specifications for performance level verification can remain valid. Power contactors with mirror contacts and contactor relays with positively driven contacts are employed in the examples below. Assumption The Emergency Stop button is actuated 1x per month. Emergency Stop is canceled and the safety switching device A1 is reset by means of button S1. Safety relay K1 and line contactor K2 are energized via the contacts of the safety switching device A1. 6SE70876QX60 Version AM Siemens AG Compendium Vector Control SIMOVERT MASTERDRIVES 12.2010 Configuration and Connection Examples Emergency Stop actuation. Observations Pulse suppression before the drive has reached standstill causes the motor to coast down. This has positive opening contacts. Fault exclusion is assumed in each case for the positive opening contacts and the mechanical components of the Emergency Stop button.

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